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Higher integrability of generalized Stokes system under perfect slip boundary conditions.

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We investigate properties of the weak solution $u: \Omega \to \mathbb{R}^n$ and $\pi : \Omega \to \mathbb{R}$ solving:

 $Stokes_{\text{p.slip}}$

$$
-\operatorname{div} S(Du) + \nabla \pi = \operatorname{div} F \text{ in } \Omega, \tag{1}
$$

$$
\text{div } u = 0 \text{ in } \Omega,\tag{2}
$$

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$$
u \cdot \nu = 0, \quad [\mathcal{S}(Du)\nu] \cdot \tau = 0 \text{ on } \partial\Omega,
$$
 (3)

where u is velocity, Du symmetric part of velocity gradient, div F density of volume forces, π kinematic pressure and Cauchy stress tensor $\mathcal T$ has the form $\mathcal{T} = -\pi \mathcal{I} + \mathcal{S}$.

N-functions

Definition

A real function $\Phi:\mathbb{R}^+\to\mathbb{R}^+$ is called N-function if there exists the derivative Φ' which is right continuous for $s > 0$, positive for $s > 0$. non-decreasing and satisfies $\Phi'(0)=0$ and $\mathit{lim}_{s\rightarrow\infty}\Phi'(s)=\infty.$

By $(\Phi')^{-1}: \mathbb{R}^+ \to \mathbb{R}^+$ we denote the function

$$
(\Phi')^{-1}(s):=\sup\{t\in\mathbb{R}^+: \Phi'(t)\leq s\}.
$$

The complementary function of Φ (which is again an N-function) is defined as

$$
\Phi^*(s):=\int_0^s(\Phi')^{-1}(t)\,\mathrm{d} t.
$$

Definition

N-function Φ is said to satisfy the Δ_2 −condition, denoted $\Phi \in \Delta_2$, if there exists a positive constant C, such that $\Phi(2s) \leq C \Phi(s)$ for $s > 0$. By $\Delta_2(\Phi)$ we denote the smallest such constant C.

We can construct $\Phi : [0, \infty) \mapsto [0, \infty)$ to S, i.e.

$$
\mathcal{S}_{ij}(A)=\partial_{ij}\Phi(|A|)=\Phi'(|A|)\frac{A_{ij}}{|A|}\quad\forall A\in\mathbb{R}_{sym}^{n\times n}.
$$

Assumption 1

We suppose that $\Phi\in \mathcal{C}^{1,1}(0,\infty)\cap \mathcal{C}^1[0,\infty)$ is N-function, $\Phi\in \Delta_2$, $\Phi^*\in \Delta_2$ and $\Phi'(s)\sim s\Phi''(s)$ holds for all $s>0,$ i.e. there exist constants $C, c > 0$ such that, for $s > 0$

$$
C\Phi'(s) \leq s\Phi''(s) \leq c\Phi'(s).
$$

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Some results will be valid for almost monotone $\Phi''(s)$, i.e. either $\Phi''(s) \leq C \Phi''(t)$ $\forall 0 < s \leq t$ (almost increasing) or $\Phi''(s) \geq C \Phi''(t) \,\forall 0 < s \leq t$ (almost decreasing). Define $V(A) = \sqrt{\Phi'(|A|)|A|} \frac{A}{|A|}$. It holds $|V(A)|^2 \sim \Phi(|A|)$.

We can consider models with a great deal of disparity, for example power-law models

$$
\mathcal{S}(Du)=\mu_0(1+|Du|^2)^{\frac{p-2}{2}}Du,\quad \Phi(|Du|)=\mu_0\int_0^{|Du|}(1+s^2)^{\frac{p-2}{2}}s\,\mathrm{d}s,
$$

$$
S(Du) = \mu_0 (1 + |Du|)^{p-2} Du, \quad \Phi(|Du|) = \mu_0 \int_0^{|Du|} (1 + s)^{p-2} s \, \mathrm{d} s,
$$

 $\mu_{0} \in \mathbb{R}^{+}$, $\rho \in (1,\infty)$. Also the singular case

$$
\mu(Du) = \mu_0 |Du|^{p-2}Du, \quad \Phi(|Du|) = \mu_0 \int_0^{|Du|} s^{p-1} ds
$$

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is included.

Theorem

Let $\Omega\subset\mathbb{R}^n$ be a $\mathcal{C}^{2,1}$ domain, $\Omega_Q=\Omega\cap Q.$ Let Assumption 1 be fulfilled and u be a weak solution to (1) – (3) . Then the following implication holds

 $\Phi^*(\vert F \vert) \in L^q(\Omega_{8Q}) \Rightarrow \Phi(\vert Du \vert) \in L^q(\Omega_{\frac{1}{2}Q}),$

provided $q\in (1,\infty)$ for $n=2$ and $q\in \left(1,\frac{n}{n-2}\right)$, resp. $q\in \left(1,\frac{n}{n-2}+\delta\right)$ for $n > 2$ and some $\delta > 0$ in case Φ'' is almost monotone. Moreover, it holds

$$
\int_{\Omega_{\frac{1}{2}Q}} \Phi(|Du|)^q dx \le c \left(\int_{\Omega_{8Q}} \Phi^* (|F|)^q dx + \int_{\Omega_{8Q}} \Phi (|u|)^q dx \right) + c \left(\int_{\Omega_{8Q}} \Phi(|Du|) dx \right)^q.
$$
 (4)

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• Our goal is the regularity up to the boundary for perfect slip boundary conditions, since the interior regularity was proven in

L. Diening, P. Kaplický: 2013

L^q theory for a generalized Stokes system, Manuscripta Mathematica

- Key parts of the proof: comparison with the homogeneous system, flattening boundary, extension solution beyond flat boundary.
- **Structure of the proof:** similar as in the paper by L. Diening and P. Kaplický. It is based on the approach published in

L. A. Caffarelli, I. Peral: 1998

On $W^{1,p}$ estimates of elliptic equation in divergence form, Comm. Pure and Appl. Math.

Lemma

Let $1\leq p < q < s < \infty$, $f \in L^{q/p}((4Q)^+)$, $g \in L^{q/p}((4Q)^+)$ and $w \in L^p((4Q)^+)^n$, where $(4Q)^+ = 4Q \cap \mathbb{R}^n_+$. Let Q_k be dyadic cubes obtained from Q with predecessor \tilde{Q}_k . If $\exists \varepsilon \in (0,\varepsilon_0) \; \forall Q_k \subset Q$ $\exists w_{\mathsf{a}} \in L^p((4\tilde{Q}_k)^+)^n$ with following properties:

$$
\begin{array}{lcl} \displaystyle \left(\displaystyle \int_{(2\tilde{Q}_k)^+}|w_a|^s \,\mathrm{d} x\right)^{\frac{1}{s}} & \leq & \displaystyle \frac{C}{2}\displaystyle \left(\displaystyle \int_{(4\tilde{Q}_k)^+}|w_a|^p \,\mathrm{d} x\right)^{\frac{1}{p}}, \\ \displaystyle & \int_{(4\tilde{Q}_k)^+}|w_a|^p \,\mathrm{d} x & \leq & \displaystyle C\displaystyle \int_{(4\tilde{Q}_k)^+}|w|^p \,\mathrm{d} x+C\displaystyle \int_{(4\tilde{Q}_k)^+}|g| \,\mathrm{d} x, \\ \displaystyle & \int_{(4\tilde{Q}_k)^+}|w-w_a|^p \,\mathrm{d} x & \leq & \displaystyle \varepsilon\displaystyle \int_{(4\tilde{Q}_k)^+}|w|^p \,\mathrm{d} x+C\displaystyle \int_{(4\tilde{Q}_k)^+}|f| \,\mathrm{d} x, \end{array}
$$

then $w \in L^q(Q)^n$. Furthermore,

$$
\int_{Q} |w|^q \, \mathrm{d} x \leq c \left(\int_{(4Q)^+} |f|^{\frac{q}{p}} \, \mathrm{d} x + \int_{(4Q)^+} |g|^{\frac{q}{p}} \, \mathrm{d} x + \left(\int_{(4Q)^+} |w|^p \, \mathrm{d} x \right)^{\frac{q}{p}} \right).
$$

Lemma

Let $1\leq p < q < s < \infty$, $f \in L^{q/p}((4Q)^+)$, $g \in L^{q/p}((4Q)^+)$ and $w \in L^p((4Q)^+)^n$, where $(4Q)^+ = 4Q \cap \mathbb{R}^n_+$. Let Q_k be dyadic cubes obtained from Q with predecessor \tilde{Q}_k . If $\exists \varepsilon \in (0,\varepsilon_0) \; \forall Q_k \subset Q$ $\exists w_{\mathsf{a}} \in L^p((4\tilde{Q}_k)^+)^n$ with following properties:

$$
\begin{array}{lcl} \displaystyle \left(\hbox{\large\it \int}_{(2\tilde{Q}_k)^+}|w_a|^s\,\mathrm{d} x\right)^{\frac{1}{s}} & \displaystyle \leq & \displaystyle \frac{C}{2}\displaystyle \left(\hbox{\large\it \int}_{(4\tilde{Q}_k)^+}|w_a|^p\,\mathrm{d} x\right)^{\frac{1}{p}}, \\ \displaystyle & \displaystyle \int_{(4\tilde{Q}_k)^+}|w_a|^p\,\mathrm{d} x & \displaystyle \leq & \displaystyle C\displaystyle \int_{(4\tilde{Q}_k)^+}|w|^p\,\mathrm{d} x+C\displaystyle \int_{(4\tilde{Q}_k)^+}|g|\,\mathrm{d} x, \\ \displaystyle & \displaystyle \int_{(4\tilde{Q}_k)^+}|w-w_a|^p\,\mathrm{d} x & \displaystyle \leq & \displaystyle \varepsilon\displaystyle \int_{(4\tilde{Q}_k)^+}|w|^p\,\mathrm{d} x+C\displaystyle \int_{(4\tilde{Q}_k)^+}|f|\,\mathrm{d} x, \end{array}
$$

then $w \in L^q(Q)^n$. Furthermore,

$$
\int_{Q} |w|^q \, \mathrm{d} x \leq c \left(\int_{(4Q)^+} |f|^{\frac{q}{p}} \, \mathrm{d} x + \int_{(4Q)^+} |g|^{\frac{q}{p}} \, \mathrm{d} x + \left(\int_{(4Q)^+} |w|^p \, \mathrm{d} x \right)^{\frac{q}{p}} \right).
$$

Consider the homogeneous system

$$
-\operatorname{div} S(Dv) + \nabla p = 0 \quad \text{in } (2Q)^+,
$$

\n
$$
\operatorname{div} v = 0 \quad \text{in } (2Q)^+,
$$

\n
$$
v \cdot \nu = 0, \quad [S(Dv)\nu] \cdot \tau = 0 \quad \text{on } \Gamma_{(2Q)^+}.
$$
 (5)

Theorem

Let $v\in W^{1,\Phi}((2Q)^+)^n$ be a local weak solution to [\(5\)](#page-10-1). Then there exists a constant C independent of v and R such that

$$
\left(\hskip-3pt{\int}_{Q^+}|V(Dv)|^q\,{\rm d} x\right)^{\frac{1}{q}}\le C\left(\hskip-3pt{\int}_{(2Q)^+}|V(Dv)|^2\,{\rm d} x\right)^{\frac{1}{2}},
$$

for $q \in \left[2, \frac{2n}{n-2}\right]$ provided $n > 2$ and $q \in \left[2, \infty\right)$ for $n = 2$. In case Φ'' is almost monotone, $n > 2$, we can even allow $q = \frac{rn}{n-r}$ for some $r > 2$.

[Formulation of the problem](#page-2-0) and the proof control of control of control of c Approximative system on a flat boundary

Proof of the theorem 1/2

At first we extend the solution from $(2Q)^+$ to 2 Q . For $\alpha=1,\ldots,n-1$ define \tilde{v} as follows

$$
\tilde{v}_{\alpha}(x',x_n) = \begin{cases}\nv_{\alpha}(x',x_n) & \text{for } x_n > 0, \\
v_{\alpha}(x',-x_n) & \text{for } x_n < 0,\n\end{cases}
$$
\n
$$
\tilde{v}_n(x',x_n) = \begin{cases}\nv_n(x',x_n) & \text{for } x_n > 0, \\
-v_n(x',-x_n) & \text{for } x_n < 0.\n\end{cases}
$$

Lemma

 $\tilde{v} \in W^{1,\Phi}(2Q)^n$ is a local weak solution to (5) extended to 2Q.

$$
\int_{Q} |\nabla V(D\tilde{\mathbf{v}})|^2 \, \mathrm{d}x \leq \frac{C}{R^2} \Bigl(\int_{2Q} |V(D\tilde{\mathbf{v}})|^2 \, \mathrm{d}x \Bigr). \tag{6}
$$

For almost monotone Φ'' the estimate [\(6\)](#page-11-0) can be improved to

$$
\int_{Q} |\nabla V(D\tilde{v})|^2 dx \leq \frac{C}{R^2} \Bigl(\int_{2Q} |V(D\tilde{v}) - \langle V(D\tilde{v}) \rangle_{2Q}|^2 dx \Bigr).
$$
 (7)

[Formulation of the problem](#page-2-0) and the state of the state of the [Main result](#page-6-0) and the state of the proof of the proof of the state of the proof of the proof of the state of th Approximative system on a flat boundary Proof of the lemma

- By reflection we have the interior problem, which is proven in [DK].
- We focus only to generalization from $n = 3$ to arbitrary $n \in \mathbb{N} \setminus \{1\}$.
- We can't test the weak formulation [\(5\)](#page-10-1) by $\varphi = \mathsf{curl}[\xi^2(\mathsf{curl}(\tilde{\nu} q))],$ since curl : $(v_1, v_2, v_3) \rightarrow (\partial_2 v_3 - \partial_3 v_2, \partial_3 v_1 - \partial_1 v_3, \partial_1 v_2 - \partial_2 v_1)$.
- We test by $\varphi = \left(\star d[\xi^2 \star d(\tilde{v} q)^{\flat}]\right)^{\sharp}$ (b converts the vector field $(\tilde{v} - q)$ into a 1-form $(\tilde{v} - q)^{\flat}$. The exterior derivative d computes something like a curl but expressed as a 2-form $d(\tilde{v} - q)^{\flat}$. The Hodge map \star turns this 2-form into a $(n-2)$ -form. After multiplication by ξ^2 and application of the derivative d we obtain $(n - 1)$ -form and Hodge star \star create 1−form, which is by] converted to the vector.
- In components:

 $\varphi=\sum_{i,j=1}^n\Big(-\xi^2\partial_i^2(\tilde{\mathsf{v}})_j+2\xi\partial_i\xi[-\partial_i(\tilde{\mathsf{v}}-{\mathsf{q}})_j+\partial_j(\tilde{\mathsf{v}}-{\mathsf{q}})_i]\Big)\mathsf{e}_j,$

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[Formulation of the problem](#page-2-0) and the proof control of co Approximative system on a flat boundary Proof of the theorem 2/2

• Follows from the lemma by application of Sobolev-Poincaré inequality (resp. Sobolev-Poincaré inequality and reverse Hölder inequality).

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$$
\bullet\ \ \tilde v\rightarrow v\ \ \text{and}\ \ Q\rightarrow Q^+,\ \text{resp.}\ \ 2Q\rightarrow (2Q)^+.
$$

Lemma

Let $1\leq p < q < s < \infty$, $f \in L^{q/p}((4Q)^+)$, $g \in L^{q/p}((4Q)^+)$ and $w \in L^p((4Q)^+)^n$, where $(4Q)^+ = 4Q \cap \mathbb{R}^n_+$. Let Q_k be dyadic cubes obtained from Q with predecessor \tilde{Q}_k . If $\exists \varepsilon \in (0,\varepsilon_0) \; \forall Q_k \subset Q$ $\exists w_{\mathsf{a}} \in L^p((4\tilde{Q}_k)^+)^n$ with following properties:

$$
\begin{array}{lcl} \displaystyle \left(\displaystyle \int_{(2\tilde{Q}_k)^+}|w_a|^s \,\mathrm{d} x\right)^{\frac{1}{s}} & \leq & \displaystyle \frac{C}{2}\displaystyle \left(\displaystyle \int_{(4\tilde{Q}_k)^+}|w_a|^p \,\mathrm{d} x\right)^{\frac{1}{p}}, \\ \displaystyle & \int_{(4\tilde{Q}_k)^+}|w_a|^p \,\mathrm{d} x & \leq & \displaystyle \int_{(4\tilde{Q}_k)^+}|w|^p \,\mathrm{d} x+C\displaystyle \int_{(4\tilde{Q}_k)^+}|g| \,\mathrm{d} x, \\ \displaystyle & \int_{(4\tilde{Q}_k)^+}|w-w_a|^p \,\mathrm{d} x & \leq & \displaystyle \varepsilon\displaystyle \int_{(4\tilde{Q}_k)^+}|w|^p \,\mathrm{d} x+C\displaystyle \int_{(4\tilde{Q}_k)^+}|f| \,\mathrm{d} x, \end{array}
$$

then $w \in L^q(Q)^n$. Furthermore,

$$
\int_{Q} |w|^{q} dx \leq c \left(\int_{(4Q)^{+}} |f|^{q \over p} dx + \int_{(4Q)^{+}} |g|^{q \over p} dx + \left(\int_{(4Q)^{+}} |w|^{p} dx \right)^{q \over p} \right).
$$

- \bullet H_R : $Q^+ \mapsto \Omega_R := H_R(Q^+) \subset \Omega$.
- It holds that $H_R(0) = x_0$ and $\nabla H_R(0) = I$.
- $\nabla H_R(x) \nabla H_R(0) = R\omega$, $\nabla H_R^{-1}(x) \nabla H_R^{-1}(0) = R\omega$.
- For $f : \Omega_R \mapsto \mathbb{R}$ we state $\overline{f} : Q^+ \mapsto \mathbb{R}$ defined as $\overline{f}(x) = f(H_R(x)) = f(y).$

$$
2D_y f = (\nabla_x \overline{f} \nabla_x H_R^{-1}) + (\nabla_x \overline{f} \nabla_x H_R^{-1})^T = 2(D_x \overline{f} + Z_{\overline{f}}),
$$

\n
$$
Z_{\overline{f}} = \frac{1}{2} (\nabla_x \overline{f} (\nabla_x H_R^{-1} - I) + (\nabla_x H_R^{-1} - I)^T (\nabla_x \overline{f})^T)
$$

\n
$$
= \frac{R}{2} (\nabla_x \overline{f} \omega + (\nabla_x \overline{f} \omega)^T),
$$

\n
$$
div_y f = \text{Tr} (\nabla_x \overline{f} \nabla_x H_R^{-1}) = div_x \overline{f} + \text{Tr}(\nabla_x \overline{f} (\nabla_x H_R^{-1} - I))
$$

\n
$$
= div_x \overline{f} + R \text{Tr}(\nabla_x \overline{f} \omega).
$$

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Transformation of the weak formulation

We can transform the weak formulation

$$
\int_{\Omega_R} \mathcal{S}(Du) : D\varphi \, \mathrm{d}y - \int_{\Omega_R} \pi \, \mathrm{div} \, \varphi \, \mathrm{d}y = \int_{\Omega_R} F : D\varphi \, \mathrm{d}y,\tag{8}
$$

which holds for all $\varphi\in W^{1,\Phi}(\Omega)^n$, $\varphi\cdot\nu=0$ on $\partial\Omega$ and $\varphi=0$ on $\partial\Omega_R \setminus \partial\Omega$ into

$$
\int_{Q^{+}} S(D\overline{u} + Z_{\overline{u}}) : (D\psi + Z_{\psi} + \omega'\psi)(1 + R\omega'') dx
$$

$$
- \int_{Q^{+}} \overline{\pi} (\operatorname{div} \psi + R \operatorname{Tr}(\omega \nabla \psi) + \operatorname{Tr}(\omega'\psi))(1 + R\omega'') dx
$$

$$
= \int_{Q^{+}} \overline{F} : (\nabla \psi + R\omega \nabla \psi + \omega'\psi)(1 + R\omega'') dx, \quad (9)
$$

which holds for all $\psi \in W^{1,\Phi}(Q^+), \psi \cdot e_n = 0$ on Γ_{Q^+} and $\psi = 0$ on $\partial Q^+ \setminus \Gamma_{Q^+}.$

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Since div $\overline{u} \neq 0$ in Q^+ and $\overline{u} \cdot e_n \neq 0$ on Γ_{Q^+} , we define a function \overline{u}_2 as a solution to

> div $\overline{u}_2 = -R \operatorname{Tr}(\nabla \overline{u} \omega)$ in $Q^+,$ $\overline{u}_2 \cdot e_n = R(\omega \overline{u}) \cdot e_n$ on Γ_{Q^+} .

The boundary condition [\(10\)](#page-17-0) comes from the fact that we want

$$
\overline{u}_2 \cdot e_n = \overline{u} \cdot e_n = (I - (\nabla H_R)^T) \overline{u} \cdot e_n + (\nabla H_R)^T \overline{u} \cdot e_n = R(\omega \overline{u}) \cdot e_n
$$
 on Γ_{Q^+} ,

To obtain estimates of \overline{u}_2 in terms of \overline{u} we use

Lemma (Bogovskiĭ)

 $\Delta_2(\{\Phi^*,\Phi\})<\infty$, $g\in L^\Phi(Q^+),\ h\in W^{1,\Phi}(Q^+)$

$$
\operatorname{div} z = g \quad in \ Q^+, \tag{10}
$$

$$
z \cdot \nu = h \cdot \nu \quad on \; \Gamma_{Q^+}, \tag{11}
$$

$$
\int_{Q^+} \Phi(|\nabla z|) dx \le C \left(\int_{Q^+} \Phi(|g|) dx + \int_{Q^+} \Phi(|\nabla h|) dx \right), \qquad (12)
$$

- Define $\overline{u}_1 = \overline{u} \overline{u}_2$.
- $\overline{u}_1 \cdot e_n = 0$ on Γ_{Q^+} and div $u_1 = 0$ in Q^+ .
- Construct v in Q^+ such that

 $v = \overline{u}_1$ on $\partial Q^+ \setminus \Gamma_{Q^+},$ $v \cdot e_n = 0$, $[\mathcal{S}(Dv)e_n] \cdot e_\alpha = 0$ on Γ_{Q^+} ,

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• Test weak formulation of [\(5\)](#page-10-1) and [\(9\)](#page-0-0) by $\varphi = \overline{u}_1 - v$ and obtain:

Lemma

$$
\int_{Q^+} |V(Dv)|^2 \, \mathrm{d}x \leq C \int_{Q^+} |V(D\overline{u})|^2 \, \mathrm{d}x + CR^{\alpha} \int_{Q^+} \Phi(|\overline{u}|) \, \mathrm{d}x,
$$

for some $\alpha > 1$ and $\theta \in (0,1)$. Furthermore, for all δ there exists a positive constant C_{δ} independent of v, \overline{u} and Q^{+} such that

$$
\int_{Q^+} |V(D\overline{u}) - V(Dv)|^2 dx \le C_\delta \int_{Q^+} \Phi^*(|F|) dx
$$

+ $(\delta + CR^\alpha) \int_{Q^+} |V(D\overline{u})|^2 dx + C \int_{Q^+} \Phi(|\overline{u}|) dx.$

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Thank you for your attention.

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