



Viscoelastic rate type fluids with stress diffusion: thermodynamic and PDE analysis

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Section 1

Viscous fluids and visco-elastic fluids
without/with stress diffusion

Unsteady flows of incompressible fluids

Governing equations

$\Omega \subset \mathbb{R}^3$

$$\begin{aligned} \operatorname{div} \mathbf{v} &= 0 \\ \frac{\partial \mathbf{v}}{\partial t} + \operatorname{div}(\mathbf{v} \otimes \mathbf{v}) &= -\nabla p + \operatorname{div} \mathbb{S} \\ \mathbb{S} &= \mathbb{S}^T \\ \mathbf{v} &= \mathbf{0} \\ \mathbf{v}(0, \cdot) &= \mathbf{v}_0 \end{aligned} \quad \left. \begin{array}{l} \\ \\ \\ \end{array} \right\} \begin{array}{l} \text{in } (0, T) \times \Omega \\ \\ \text{on } (0, T) \times \partial\Omega \\ \text{in } \Omega \end{array}$$

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Energy balance

$$\frac{1}{2} \frac{\partial |\mathbf{v}|^2}{\partial t} + \operatorname{div} \left(\frac{|\mathbf{v}|^2}{2} \mathbf{v} + p\mathbf{v} - \mathbb{S}\mathbf{v} \right) + \mathbb{S} : \nabla \mathbf{v} = 0$$

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$$\frac{d}{dt} \int_{\Omega} |\mathbf{v}|^2 + 2 \int_{\Omega} \mathbb{S} : \nabla \mathbf{v} + \int_{\partial\Omega} (|\mathbf{v}|^2 + 2p)(\mathbf{v} \cdot \mathbf{n}) - 2\mathbb{S} : (\mathbf{v} \otimes \mathbf{n}) = 0$$

Energy estimates and constitutive equations

- Governing equations

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$$\mathbb{D} := \frac{1}{2} (\nabla \mathbf{v} + (\nabla \mathbf{v})^T)$$

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- To close the system

we add a material dependent relation involving \mathbb{S} and \mathbb{D}

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Constitutive equations

Classes of constitutive equations

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- (1) $G(\mathbb{S}, \mathbb{D}) = \mathbb{O}$
implicit algebraic equations
- (2) $G(\overset{*}{\mathbb{S}}, \overset{*}{\mathbb{S}}, \overset{*}{\mathbb{D}}, \overset{*}{\mathbb{D}}) = \mathbb{O}$ $\overset{*}{\mathbb{A}}$ an objective time derivative
rate type viscoelastic fluids
- (3) $G(\overset{*}{\mathbb{S}}, \overset{*}{\mathbb{S}}, \overset{*}{\mathbb{D}}, \overset{*}{\mathbb{D}}) - \Delta \mathbb{S} = \mathbb{O}$
rate type viscoelastic fluids with stress diffusion

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rate type viscoelastic fluids with stress diffusion
- Examples and physical features
 - PDE analysis of IBVP (long time existence of large data weak solutions)

$$S = 2\nu D$$

Navier-Stokes

$$2\nu(|S|^2, |D|^2)D = 2\alpha(|S|^2, |D|^2)S$$

generalized viscosity

$$2\nu D = \frac{(|S| - \sigma_*)^+}{|S|} S$$

Bingham

$$2\nu \frac{(|D| - d_*)^+}{|D|} D = S$$

Euler/Navier-Stokes

$$2\nu(\theta) \frac{(|D| - d(\theta))^+}{|D|} D = \frac{(|S| - \sigma(\theta))^+}{|S|} S$$

 θ -activated fluids

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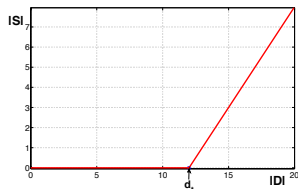
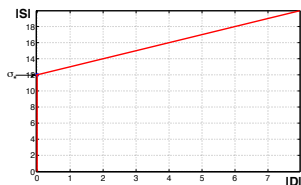
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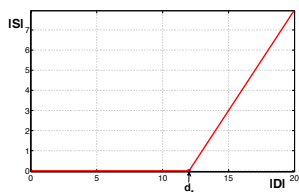
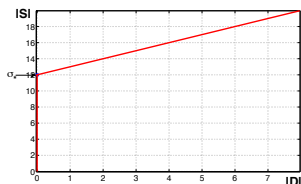
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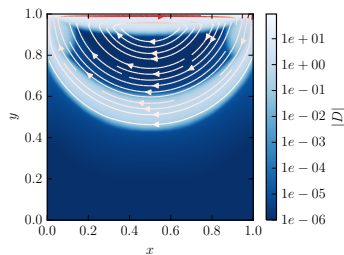
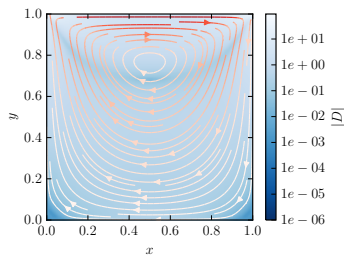
Euler/Navier-Stokes

$$2\nu(\theta) \frac{(|D| - d(\theta))^+}{|D|} D = \frac{(|S| - \sigma(\theta))^+}{|S|} S \quad \theta\text{-activated fluids}$$



Robustness of $\mathbb{G}(\mathbb{S}, \mathbb{D}) = \mathbb{O}$

$$2\nu\mathbb{D} = \frac{(|\mathbb{S}| - \sigma_*)^+}{|\mathbb{S}|} \mathbb{S}$$



J. Hron, J. Málek, J. Stebel, K. Touška: A novel view on computations of steady flows of Bingham fluids using implicit constitutive relations, MORE/2017/08 (2017)

Long-time and large-data theory for $\mathbb{G}(\mathbb{S}, \mathbb{D}) = \mathbb{O}$

- Well-posedness

- $2d \mathbb{S} = 2\nu \mathbb{D}$

Leray; Kiselev, Ladyzhenskaya

- $3d \mathbb{S} = 2(\nu + \nu_1 |\mathbb{D}|^{r-2}) \mathbb{D}$ for $r \geq 11/5$

Ladyzhenskaya; Bulíček, Ettwein, Kaplický, Pražák

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- Existence theory

- $3d \mathbb{S} = 2\nu\mathbb{D}$ Leray; Caffarelli, Kohn, Nirenberg
- $3d \mathbb{S} = 2\nu(1 + |\mathbb{D}|^2)^{(r-2)/2}\mathbb{D}$ for $r \geq 9/5$
Bellout, Bloom, Nečas, Málek, Růžička
- $3d \mathbb{S} = 2\nu(1 + |\mathbb{D}|^2)^{(r-2)/2}\mathbb{D}$ for $r \geq 8/5$
Frehse, Steinhauer, Bulíček, Málek; Wolf
- $3d \mathbb{S} = 2\nu(1 + |\mathbb{D}|^2)^{(r-2)/2}\mathbb{D}$ for $r > 6/5$
Diening, Růžička, Wolf; Breit, Diening, Schwarzacher
- $3d \mathbb{G}(\mathbb{S}, \mathbb{D}) = \mathbb{O}$ maximal, monotone, r -curve with $r > 6/5$
Bulíček, Gwiazda, Málek, Świerczewska-Gwiazda

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Q: How large the class of fluids might be for which long-time and large-data existence of weak solutions can be established?

From viscous to elastic fluids through viscoelastic rate type fluids.

Insufficiency of $\mathbb{G}(\mathbb{S}, \mathbb{D}) = \mathbb{O}$

Impossibility to describe important phenomena

- nonlinear creep
- stress relaxation

exhibited by real fluid-like materials in many areas

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Popular choice

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Popular choice

rate type viscoelastic fluids

$G(\overset{*}{S}, \overset{*}{S}, \overset{*}{D}, \overset{*}{D}) = \mathbb{O}$ - rate-type viscoelastic fluids

- capability of describing stress relaxation and nonlinear creep
- one possible direction towards the development of long-time and large-data mathematical theory for more complex fluid models

$G(\overset{*}{\mathbb{S}}, \overset{*}{\mathbb{S}}, \overset{*}{\mathbb{D}}, \overset{*}{\mathbb{D}}) = \mathbb{O}$ - rate-type viscoelastic fluids

- capability of describing stress relaxation and nonlinear creep
- one possible direction towards the development of long-time and large-data mathematical theory for more complex fluid models

$\overset{*}{\mathbb{A}}$ generalizes $\frac{d}{dt}\mathbb{A} = \frac{\partial\mathbb{A}}{\partial t} + (\mathbf{v} \cdot \nabla)\mathbb{A}$ that is **not objective**

$$\overset{\nabla}{\mathbb{A}} = \frac{d}{dt}\mathbb{A} - \mathbb{L}\mathbb{A} - \mathbb{A}\mathbb{L}^T \quad \mathbb{L} := \nabla\mathbf{v}$$

upper-convected Oldroyd

$$\overset{\circ}{\mathbb{A}} = \frac{d}{dt}\mathbb{A} - \mathbb{W}\mathbb{A} - \mathbb{A}\mathbb{W}^T \quad \mathbb{W} := (\mathbb{L} - \mathbb{L}^T)/2$$

Jaumann-Zaremba (corotational)

$$\overset{\square}{\mathbb{A}} = \overset{\circ}{\mathbb{A}} - a(\mathbb{D}\mathbb{A} - \mathbb{A}\mathbb{D}) \quad a \in [-1, 1]$$

Gordon-Schowalter

Standard viscoelastic rate-type fluid models within

$$\mathbb{G}(\overset{*}{\mathbb{S}}, \overset{*}{\mathbb{S}}, \overset{*}{\mathbb{D}}, \overset{*}{\mathbb{D}}) = \mathbb{O}$$

- Maxwell (1867)

$$\boxed{\overset{\nabla}{\tau}\overset{\nabla}{\mathbb{S}} + \overset{\nabla}{\mathbb{S}} = 2\nu_1\overset{\nabla}{\mathbb{D}} \quad \nu = 0} \quad \tau = \frac{\nu_1}{E}$$

- Oldroyd-B (1950)

$$\boxed{\overset{\nabla}{\tau}\overset{\nabla}{\mathbb{S}} + \overset{\nabla}{\mathbb{S}} = 2\nu\tau\overset{\nabla}{\mathbb{D}} + 2(\nu_1 + \nu)\overset{\nabla}{\mathbb{D}}} \quad \tau = \frac{\nu_1}{E}$$

- Johnson-Segalman (1977)

$$\boxed{\overset{\square}{\tau}\overset{\square}{\mathbb{S}} + \overset{\square}{\mathbb{S}} = 2\nu\tau\overset{\square}{\mathbb{D}} + 2(a + \nu)\overset{\square}{\mathbb{D}}} \quad a \in [-1, 1]$$

± of standard rate type fluids

+ $\mathbb{G}(\overset{*}{\mathbb{S}}, \overset{*}{\mathbb{S}}, \overset{*}{\mathbb{D}}, \overset{*}{\mathbb{D}}) = \mathbb{O}$ is capable of describing observed phenomena

+/- Mathematical theory available in some cases - first order PDE for \mathbb{S}

- 3d, Jaumann-Zaremba: Lions, Masmoudi (2000), Hu, Lelièvre (2007), Masmoudi (2011)
- survey: Le Bris, Lelièvre (2012)

- Subtle issues regarding physical underpinnings

- ambiguity of objective derivatives
- the possibility of the derivation of the model at a purely macroscopic level
- consistency of the models with second law of thermodynamics
- extension to compressible setting
- inclusion of thermal effects

Thermodynamical framework

Rajagopal and Srinivasa (2000) provided a simple, yet general method to solve some of these issues based on

- concept of the natural configuration
- the knowledge of constitutive equations for *two scalar quantities*: Helmholtz free energy (characterizing how the material stores the energy) and the rate of the entropy production (characterizing how the material dissipates the energy)

and

- derive new thermodynamically compatible classes of *non-linear* viscoelastic rate-type fluid model
- specify under what conditions models reduce to standard models

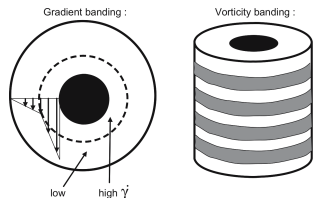


K. R. Rajagopal, A. R. Srinivasa: A thermodynamic framework for rate type fluid models, *Journal of Non-Newtonian Fluid Mechanics*, Vol. 88, pp. 207–227 (2000)

$$G^*(\mathbb{S}, \mathbb{S}, \mathbb{D}, \mathbb{D}) - \Delta \mathbb{S} = \mathbb{O}$$

+ Both mathematical and physical

- regularization (mathematical theory should be available)
 - steady flows: El-Kareh, Leal (1989)
 - 2d, Oldroyd: Barrett, Boyaval (2011)
 - 2d: Constantin+Kliegl (2012), Chupin+Martin (2015)
Lukáčová, Mizerová, Nečasová (2015)
Elgindi, Rousset (2016), Barrett, Süli (2017)
 - 3d, stronger regularization: Kreml, Pokorný, Šalom (2015)
- instabilities: shear banding, vorticity banding - to determine thickness of bands



Dhont and Briels (2008)

Divoux et al. (2016)

$$G(\overset{*}{\mathbb{S}}, \overset{*}{\mathbb{S}}, \overset{*}{\mathbb{D}}, \overset{*}{\mathbb{D}}) - \Delta \mathbb{S} = \mathbb{O}$$

- Subtle issues regarding physical underpinnings
 - consistency of the models with the second law of thermodynamics
 - specification of boundary conditions for \mathbb{S}
 - extension to compressible setting
 - inclusion of thermal effects
 - PDE theory in 3d

Section 2

**A thermodynamic approach towards
derivation of a hierarchy of visco-elastic
rate-type fluid models**

First key idea

Rajagopal and Srinivasa (2000, 2004)

to specify the constitutive equations for **two scalar** quantities:

- **Helmholtz free energy ψ** that describes how the material stores the energy
- **the rate of the entropy production ζ** that describes how the material dissipates the energy

Governing equations

$$\frac{d\rho}{dt} = -\rho \operatorname{div} \mathbf{v}$$

$$\rho \frac{d\mathbf{v}}{dt} = \operatorname{div} \mathbb{T}, \quad \mathbb{T} = \mathbb{T}^T$$

$$\rho \frac{de}{dt} = \mathbb{T} : \mathbb{D} - \operatorname{div} \mathbf{j}_e$$

$$\rho \frac{d\eta}{dt} + \operatorname{div} \mathbf{j}_\eta = \rho \zeta \quad \text{with } \zeta \geq 0$$

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$$\psi := e - \theta \eta$$

Helmholtz free energy

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Helmholtz free energy

Restriction to isothermal processes

$$\mathbb{T} : \mathbb{D} - \rho \frac{d\psi}{dt} - \operatorname{div}(\mathbf{j}_e - \theta \mathbf{j}_\eta) = \xi \quad \text{with } \xi := \theta \rho \zeta \geq 0$$

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If $\mathbf{j}_\eta = \frac{\mathbf{j}_e}{\theta}$ (not necessarily required here), then

$$\xi = \mathbb{T} : \mathbb{D} - \rho \frac{d\psi}{dt} \quad \text{with } \xi \geq 0$$

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or for incompressible fluid when $\mathbb{T} = -p\mathbb{I} + \mathbb{S}$

$$\xi = \mathbb{S} : \mathbb{D} - \rho \frac{d\psi}{dt} \quad \text{with } \xi \geq 0$$

Energy estimates and specification of ψ and ξ

- Energy equality valid for $t \in (0, T]$

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$$\|\mathbf{v}(t)\|_2^2 + 2 \int_0^t \int_{\Omega} \mathbb{S} : \mathbb{D} = \|\mathbf{v}_0\|_2^2$$

- Reduced thermodynamical identity

$$\xi = \mathbb{S} : \mathbb{D} - \frac{d\psi}{dt} \quad \text{with } \xi \geq 0$$

Energy estimates and specification of ψ and ξ

- Energy equality valid for $t \in (0, T]$

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- Specification of the constitutive equations of ψ and ξ

$$\psi = \tilde{\psi}(\dots) \quad \xi = \tilde{\xi}(\dots)$$

Energy estimates and specification of ψ and ξ

- Energy equality valid for $t \in (0, T]$

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$$\xi = \mathbb{S} : \mathbb{D} - \frac{d\psi}{dt} \quad \text{with } \xi \geq 0$$

- Specification of the constitutive equations of ψ and ξ

$$\psi = \tilde{\psi}(\dots) \quad \xi = \tilde{\xi}(\dots)$$

- Updated energy equality

$$\|\mathbf{v}(t)\|_2^2 + \|\tilde{\psi}(\dots)(t)\|_1 + 2 \int_0^t \int_{\Omega} \tilde{\xi}(\dots) = \|\mathbf{v}_0\|_2^2 + \|\tilde{\psi}_0(\dots)\|_1$$

General thermodynamic framework

Constitutive equation for the **Helmholtz free energy** ψ :

$$\boxed{\psi = \tilde{\psi}(y_1, \dots, y_N)} \quad (1)$$

By means of balance equations (mass, linear and angular momenta, energy) and kinematics one arrives at

$$\xi = \mathbb{T} : \mathbb{D} - \rho \frac{d\psi}{dt} \stackrel{(1)}{=} \sum_{\alpha} J_{\alpha} A_{\alpha} \quad \text{with}$$

Constitutive equation for **the rate of dissipation** ξ :

$$\boxed{\xi = \sum_{\alpha} \gamma_{\alpha} |A_{\alpha}|^2}$$

leads to

$$J_{\alpha} = \gamma_{\alpha} A_{\alpha} \quad \gamma_{\alpha} > 0$$

Compressible and incompressible Navier-Stokes fluids

$$\psi = \psi_0(\varrho)$$

$$p_{\text{th}}(\varrho) := \varrho^2 \psi'_0(\varrho)$$

$$\xi = \mathbb{T} : \mathbb{D} - \varrho \frac{d\psi}{dt} \quad \Longrightarrow \quad \xi = \mathbb{T}_\delta : \mathbb{D}_\delta + (m + p_{\text{th}}) \operatorname{div} \mathbf{v}$$

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$$\xi = 2\nu \mathbb{D}_\delta : \mathbb{D}_\delta + \frac{2\nu + 3\lambda}{3} |\operatorname{div} \mathbf{v}|^2$$

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$$\mathbb{T} = m\mathbb{I} + \mathbb{T}_\delta = -p_{\text{th}}\mathbb{I} + 2\nu \mathbb{D} + \lambda \operatorname{div} \mathbf{v} \mathbb{I}$$

Compressible NS

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$$\mathbb{T} = m\mathbb{I} + \mathbb{T}_\delta = -p_{\text{th}}\mathbb{I} + 2\nu \mathbb{D} + \lambda \operatorname{div} \mathbf{v} \mathbb{I}$$

Compressible NS

$$\operatorname{div} \mathbf{v} = 0$$

$$\xi = \mathbb{T}_\delta : \mathbb{D}_\delta \quad \text{with } \xi \geq 0$$

$$\xi = 2\nu \mathbb{D}_\delta : \mathbb{D}_\delta$$

Compressible and incompressible Navier-Stokes fluids

$$\psi = \psi_0(\varrho)$$

$$p_{\text{th}}(\varrho) := \varrho^2 \psi_0'(\varrho)$$

$$\xi = \mathbb{T} : \mathbb{D} - \varrho \frac{d\psi}{dt} \quad \Longrightarrow \quad \xi = \mathbb{T}_\delta : \mathbb{D}_\delta + (m + p_{\text{th}}) \operatorname{div} \mathbf{v}$$

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$$\operatorname{div} \mathbf{v} = 0$$

$$\xi = \mathbb{T}_\delta : \mathbb{D}_\delta \quad \text{with } \xi \geq 0$$

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$$\mathbb{T} = m\mathbb{I} + \mathbb{T}_\delta = m\mathbb{I} + 2\nu \mathbb{D}_\delta$$

Incompressible Navier-Stokes

Elastic and Kelvin-Voigt incompressible solids

$$\psi = \frac{\mu}{2\rho}(\text{tr } \mathbb{B} - 3)$$

$$\mathbb{B} := \mathbb{F}\mathbb{F}^T$$

Elastic and Kelvin-Voigt incompressible solids

$$\psi = \frac{\mu}{2\rho}(\operatorname{tr} \mathbb{B} - 3) \quad \mathbb{B} := \mathbb{F}\mathbb{F}^T$$

Since $\frac{d\mathbb{F}}{dt} = \mathbb{L}\mathbb{F}$, we get

$$\frac{d\mathbb{B}}{dt} = \mathbb{L}\mathbb{B} + \mathbb{B}\mathbb{L}^T \iff \overset{\nabla}{\mathbb{B}} = \mathbb{O} \quad \text{and} \quad \frac{d}{dt} \operatorname{tr} \mathbb{B} = 2\mathbb{B} : \mathbb{D}$$

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Hence $\xi = \mathbb{T} : \mathbb{D} - \rho \frac{d\psi}{dt}$ with $\xi \geq 0$

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$$\xi = (\mathbb{T} - \mu\mathbb{B}) : \mathbb{D} = (\mathbb{T}_\delta - \mu\mathbb{B}_\delta) : \mathbb{D} \quad \text{with } \xi \geq 0$$

Elastic and Kelvin-Voigt incompressible solids

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$$\boxed{\xi = 0} \implies \boxed{\mathbb{T} = m\mathbb{I} + \mu\mathbb{B}_\delta = -p\mathbb{I} + \mu\mathbb{B}}$$

Incompressible neo-Hookean solid

Elastic and Kelvin-Voigt incompressible solids

$$\psi = \frac{\mu}{2\rho}(\text{tr } \mathbb{B} - 3) \quad \mathbb{B} := \mathbb{F}\mathbb{F}^T$$

Since $\frac{d\mathbb{F}}{dt} = \mathbb{L}\mathbb{F}$, we get

$$\frac{d\mathbb{B}}{dt} = \mathbb{L}\mathbb{B} + \mathbb{B}\mathbb{L}^T \iff \overset{\nabla}{\mathbb{B}} = \mathbb{O} \quad \text{and} \quad \frac{d}{dt} \text{tr } \mathbb{B} = 2\mathbb{B} : \mathbb{D}$$

Hence $\xi = \mathbb{T} : \mathbb{D} - \rho \frac{d\psi}{dt}$ with $\xi \geq 0$

$$\xi = (\mathbb{T} - \mu\mathbb{B}) : \mathbb{D} = (\mathbb{T}_\delta - \mu\mathbb{B}_\delta) : \mathbb{D} \quad \text{with } \xi \geq 0$$

$$\xi = 0 \implies \mathbb{T} = m\mathbb{I} + \mu\mathbb{B}_\delta = -p\mathbb{I} + \mu\mathbb{B}$$

Incompressible neo-Hookean solid

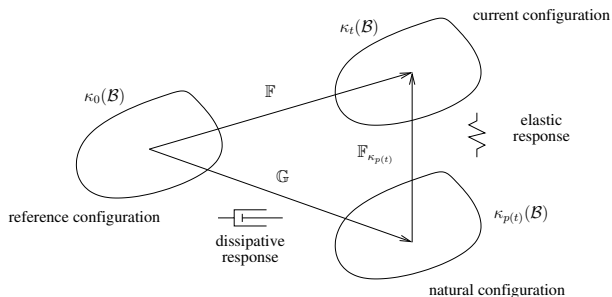
$$\xi = 2\nu\mathbb{D} : \mathbb{D} \implies \mathbb{T} = -p\mathbb{I} + \mu\mathbb{B} + 2\nu\mathbb{D}$$

Incompressible Kelvin-Voigt solid

Second key idea - Natural configuration

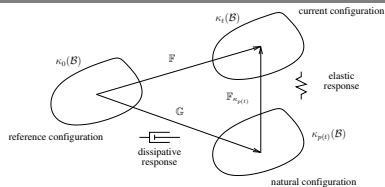
Natural configuration

- splits the deformation \mathbb{F} into the elastic and dissipative parts $\mathbb{F}_{\kappa_p(t)}$ and \mathbb{G}



- $$\mathbb{F} = \mathbb{F}_{\kappa_p(t)} \mathbb{G}$$

Kinematics



- $$\mathbb{F} = \mathbb{F}_{\kappa_{p(t)}} \mathbb{G}$$

- $F, G, F_{\kappa_{p(t)}} \quad \mathbb{B}_{\kappa_{p(t)}} := F_{\kappa_{p(t)}} F_{\kappa_{p(t)}}^T \quad \mathbb{C}_{\kappa_{p(t)}} := F_{\kappa_{p(t)}}^T F_{\kappa_{p(t)}}$
- $\frac{dF}{dt} = LF \implies L = \frac{dF}{dt} F^{-1} \quad D, W$
- $L_{\kappa_{p(t)}} := \frac{dG}{dt} G^{-1} \quad D_{\kappa_{p(t)}}, W_{\kappa_{p(t)}}$

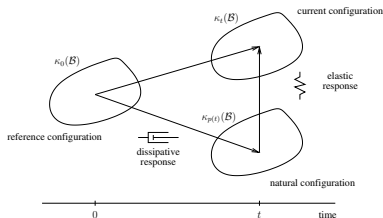
$$\frac{d\mathbb{B}_{\kappa_{p(t)}}}{dt} = L\mathbb{B}_{\kappa_{p(t)}} + \mathbb{B}_{\kappa_{p(t)}}L^T - 2F_{\kappa_{p(t)}}D_{\kappa_{p(t)}}F_{\kappa_{p(t)}}^T \implies$$

$$\nabla \mathbb{B}_{\kappa_{p(t)}} = -2F_{\kappa_{p(t)}}D_{\kappa_{p(t)}}F_{\kappa_{p(t)}}^T$$

$$\frac{d}{dt} \text{tr} \mathbb{B}_{\kappa_{p(t)}} = 2\mathbb{B}_{\kappa_{p(t)}} : D - 2\mathbb{C}_{\kappa_{p(t)}} : D_{\kappa_{p(t)}}$$

Compressible and Incompressible responses/Maxwell & Oldroyd-B

Natural configuration provides more variants for imposing compressibility



$$\psi = \frac{\mu}{2\rho} (\text{tr } \mathbb{B}_{\kappa_{p(t)}} - 3 - \ln \det \mathbb{B}_{\kappa_{p(t)}})$$

$$\xi = 2\nu \mathbb{D} : \mathbb{D} + 2\nu_1 \mathbb{D}_{\kappa_{p(t)}} \mathbb{C}_{\kappa_{p(t)}} : \mathbb{D}_{\kappa_{p(t)}} = 2\nu |\mathbb{D}|^2 + 2\nu_1 \text{tr}(\overset{\nabla}{\mathbb{B}}_{\kappa_{p(t)}} \mathbb{B}_{\kappa_{p(t)}}^{-1} \overset{\nabla}{\mathbb{B}}_{\kappa_{p(t)}})$$

lead to Maxwell and Oldroyd-B fluid



J. Málek, K. R. Rajagopal, K. Tůma: On a variant of the Maxwell and Oldroyd-B models within the context of a thermodynamic basis, *International Journal of Nonlinear Mechanics*, Vol. 76, pp. 42–47 (2015)



J. Málek, V. Průša: Derivation of equations of continuum mechanics and thermodynamics of fluids, *Handbook of Mathematical Analysis in Mechanics of Viscous Fluids*, (eds. Y. Giga, A. Novotný), Springer available online (2017)

Rate-type fluids with stress diffusion

$$\mathbb{T} : \mathbb{D} - \varrho \dot{\psi} - \operatorname{div}(\mathbf{j}_e - \theta \mathbf{j}_\eta) = \xi \text{ with } \xi \geq 0$$

Helmholtz free energy ψ – compressible neo-Hookean

$$\psi = \frac{\mu}{2\rho} (\operatorname{tr} \mathbb{B}_{\kappa_{p(t)}} - 3 - \ln \det \mathbb{B}_{\kappa_{p(t)}}) + \frac{\sigma}{2} |\nabla \operatorname{tr} \mathbb{B}_{\kappa_{p(t)}}|^2$$

Rate of entropy production ξ

$$0 \leq \tilde{\xi} = 2\nu |\mathbb{D}|^2 + 2\nu_1 \mathbb{D}_{\kappa_{p(t)}} \mathbb{C}_{\kappa_{p(t)}} : \mathbb{D}_{\kappa_{p(t)}}.$$

Maxwell and Oldroyd-B model with stress diffusion

Rate-type fluids with stress diffusion

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Maxwell and Oldroyd-B model with stress diffusion



J. Málek, V. Průša, T. Skřivan, E. Süli: Thermodynamics of viscoelastic rate type fluids with stress diffusion, arXiv: 1706.06277 (2017)

Special class of rate-type fluids with stress diffusion

Simplification $[\mathbb{C}_{\kappa_p(t)}]_{\delta} = \mathbb{O} \implies [\mathbb{B}_{\kappa_p(t)}]_{\delta} = \mathbb{O}$

$$\mathbb{C}_{\kappa_p(t)} = \mathbb{B}_{\kappa_p(t)} = b \mathbb{I} \quad \text{where } b := \frac{\text{tr } \mathbb{C}_{\kappa_p(t)}}{3} = \frac{\text{tr } \mathbb{B}_{\kappa_p(t)}}{3}$$

Special class of rate-type fluids with stress diffusion

Simplification $[\mathbb{C}_{\kappa_p(t)}]_{\delta} = \mathbb{O} \implies [\mathbb{B}_{\kappa_p(t)}]_{\delta} = \mathbb{O}$

$$\mathbb{C}_{\kappa_p(t)} = \mathbb{B}_{\kappa_p(t)} = b\mathbb{I} \quad \text{where } b := \frac{\text{tr } \mathbb{C}_{\kappa_p(t)}}{3} = \frac{\text{tr } \mathbb{B}_{\kappa_p(t)}}{3}$$

Then

$$\frac{db}{dt} = -\frac{2}{3} b \text{tr } \mathbb{D}_{\kappa_p(t)}$$

$$\xi = (\mathbb{T}_{\delta} + 9\sigma(\nabla b \otimes \nabla b)_{\delta}) : \mathbb{D} + (3\mu(b-1) - 18\sigma b \Delta b) \frac{\text{tr } \mathbb{D}_{\kappa_p(t)}}{3}$$

Requiring that

$$\xi = 2\nu \mathbb{D} : \mathbb{D} + 2\nu_1 (\text{tr } \mathbb{D}_{\kappa_p(t)})^2 = 2\nu \mathbb{D} : \mathbb{D} + \frac{\nu_1}{2} \frac{1}{b^2} \left| \frac{db}{dt} \right|^2$$

$$\begin{aligned} \mathbb{T} &= m\mathbb{I} + 2\nu \mathbb{D} - 9\sigma(\nabla b \otimes \nabla b)_{\delta} = -p\mathbb{I} + 2\nu \mathbb{D} - 9\sigma(\nabla b \otimes \nabla b) \\ \frac{\nu_1}{b} \frac{db}{dt} + 3\mu(b-1) - 18\sigma b \Delta b &= 0 \end{aligned}$$

Boundary conditions and energy estimates

$$\mathbb{S} : \mathbb{D} - \rho \dot{\psi} - \operatorname{div}(\mathbf{j}_e - \theta \mathbf{j}_\eta) = \xi$$

Summary for the special choice $[\mathbb{B}_{\kappa_p(t)}]_\delta = \mathbb{O}$

$$\mathbf{j}_e - \theta \mathbf{j}_\eta = 9\sigma \frac{db}{dt} \nabla b$$

$$\psi = \frac{3\mu}{2}(b - 1 - \ln b) + \frac{9\sigma}{2} |\nabla b|^2$$

$$\xi = 2\nu |\mathbb{D}|^2 + \frac{\nu_1}{2} \left| \frac{1}{b} \frac{db}{dt} \right|^2$$

Energy estimates

$$\begin{aligned} & \frac{\partial}{\partial t} \left(\frac{|\mathbf{v}|^2}{2} + \frac{3\mu}{2}(b - 1 - \ln b) + \frac{9\sigma}{2} |\nabla b|^2 \right) \\ & + 2\nu |\mathbb{D}|^2 + \frac{\nu_1}{2} \left| \frac{1}{b} \frac{db}{dt} \right|^2 \\ & + \operatorname{div} \left(\left(\frac{3\mu}{2}(b - 1 - \ln b) + \frac{9\sigma}{2} + \frac{|\mathbf{v}|^2}{2} \right) \mathbf{v} + \mathbb{T} \mathbf{v} + 9\sigma \frac{db}{dt} \nabla b \right) = 0 \end{aligned}$$

BCs: $\mathbf{v} = \mathbf{0}$ and $\nabla b \cdot \mathbf{n} = 0$ eliminates the contribution of the flux term to EEs

Section 3

Analysis of the simplified problem

Problem formulation

PDEs in $(0, T) \times \Omega$

$\Omega \subset \mathbb{R}^d$

$$\begin{aligned} \operatorname{div} \mathbf{v} &= 0 \\ \frac{\partial \mathbf{v}}{\partial t} + \operatorname{div}(\mathbf{v} \otimes \mathbf{v}) &= -\nabla p + \Delta \mathbf{v} - \operatorname{div}(\nabla b \otimes \nabla b) \\ \frac{\partial b}{\partial t} + \operatorname{div}(b\mathbf{v}) + (b^2 - b) - b^2 \Delta b &= 0 \end{aligned}$$

Boundary and initial conditions

$$\begin{array}{lll} \mathbf{v} = \mathbf{0} & \nabla b \cdot \mathbf{n} = 0 & \text{on } (0, T) \times \partial\Omega \\ \mathbf{v}(0, \cdot) = \mathbf{v}_0 & b(0, \cdot) = b_0 & \text{in } \Omega \end{array}$$

Energy estimates

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int_{\Omega} |\mathbf{v}|^2 + (b - 1 - \ln b) + |\nabla b|^2 \, dx \\ + \int_{\Omega} 2|\mathbb{D}|^2 + \left| \frac{1}{b} \frac{db}{dt} \right|^2 \, dx = 0 \end{aligned}$$

Problem formulation

PDEs in $(0, T) \times \Omega$

$\Omega \subset \mathbb{R}^d$

$$\begin{aligned} \operatorname{div} \mathbf{v} &= 0 \\ \frac{\partial \mathbf{v}}{\partial t} + \operatorname{div}(\mathbf{v} \otimes \mathbf{v}) &= -\nabla p + \Delta \mathbf{v} - \operatorname{div}(\nabla b \otimes \nabla b) \\ \frac{1}{b^2} \left(\frac{\partial b}{\partial t} + \nabla b \cdot \mathbf{v} \right) + (1 - b^{-1}) - \Delta b &= 0 \end{aligned}$$

Boundary and initial conditions

$$\begin{array}{lll} \mathbf{v} = \mathbf{0} & \nabla b \cdot \mathbf{n} = 0 & \text{on } (0, T) \times \partial\Omega \\ \mathbf{v}(0, \cdot) = \mathbf{v}_0 & b(0, \cdot) = b_0 & \text{in } \Omega \end{array}$$

Energy estimates

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int_{\Omega} |\mathbf{v}|^2 + (b - 1 - \ln b) + |\nabla b|^2 \, dx \\ + \int_{\Omega} 2|\mathbb{D}|^2 + \frac{1}{b^2} \left| \frac{\partial b}{\partial t} + \nabla b \cdot \mathbf{v} \right|^2 \, dx = 0 \end{aligned}$$

Existence result

Assumption on $(\mathbf{v}_0, b_0 > 0)$

$$\mathbf{v}_0 \in L^2_{0,\text{div}}(\Omega), \quad b_0 \in W^{1,2}(\Omega), \quad b_0, b_0^{-1} \in L^\infty(\Omega)$$

Theorem (Bulíček, Málek, Průša, Süli (2017))

Let $\Omega \subset \mathbb{R}^d$ be a Lipschitz set. Then there exists a couple (\mathbf{v}, b) :

$$\begin{aligned} \mathbf{v} &\in L^\infty(0, T; L^2_{0,\text{div}}) \cap L^2(0, T; W^{1,2}_{0,\text{div}}) \\ b &\in L^\infty(0, T; W^{1,2}(\Omega)), \quad b, b^{-1} \in L^\infty(Q) \\ \partial_t b + \nabla b \cdot \mathbf{v} &\in L^2(Q), \quad \Delta b \in L^2(Q) \end{aligned}$$

s.t. for a.a. $t \in (0, T)$ and all $\mathbf{w} \in W^{1,2}_{0,\text{div}} \cap W^{d+1,2}(\Omega)^d$, $w \in W^{1,2}(\Omega)$:

$$\langle \partial_t \mathbf{v}, \mathbf{w} \rangle + \int_{\Omega} (2\mathbb{D} - \nabla b \otimes \nabla b - \mathbf{v} \otimes \mathbf{v}) : \nabla \mathbf{w} \, dx = 0$$

$$\int_{\Omega} \left(\frac{\partial_t b + \nabla b \cdot \mathbf{v}}{b^2} + \left(1 - \frac{1}{b}\right) \right) w + \nabla b \cdot \nabla w \, dx = 0$$

Structure of the proof

$$T_n(s) := \min \{n, \max\{n^{-1}, s\}\} \text{ for } s \in \mathbb{R}.$$

Truncated system

$$\mathbf{v}^{n,\ell}(t, x) := \sum_{i=1}^n \alpha_i^{n,\ell}(t) \mathbf{w}_i(x), \quad b^{n,\ell}(t, x) := \sum_{i=1}^{\ell} \beta_i^{n,\ell}(t) w_i(x)$$

$$\int_{\Omega} \partial_t \mathbf{v}^{n,\ell} \cdot \mathbf{w}_i - \mathbf{v}^{n,\ell} \otimes \mathbf{v}^{n,\ell} : \nabla \mathbf{w}_i + \mathbb{S}^{n,\ell} : \nabla \mathbf{w}_i \, dx = 0$$

$i = 1, \dots, n$

$$\int_{\Omega} \frac{\partial_t b^{n,\ell} w_j}{(T_n(b^{n,\ell}))^2} + \frac{\nabla b^{n,\ell} \cdot \mathbf{v}^{n,\ell}}{(T_n(b^{n,\ell}))^2} w_j + (1 - (T_n(b^{n,\ell}))^{-1}) w_j \, dx$$
$$+ \int_{\Omega} \nabla b^{n,\ell} \cdot \nabla w_j \, dx = 0 \quad j = 1, \dots, \ell$$

$$\mathbb{S}^{n,\ell} = 2\mathbb{D}^{n,\ell} - (\nabla b^{n,\ell} \otimes \nabla b^{n,\ell}), \quad 2\mathbb{D}^{n,\ell} = \nabla \mathbf{v}^{n,\ell} + (\nabla \mathbf{v}^{n,\ell})^T$$

- Galerkin both in \mathbf{v} and b solved by Rothe's method
- $\ell \rightarrow \infty$, Galerkin in \mathbf{v} : maximum and minimum principle for b
- uniform estimates for \mathbf{v}^n, b^n mimicking the formal a priori info
- $n \rightarrow \infty$





Weak stability

$$\begin{aligned}\lim_{n \rightarrow \infty} \int_0^T \|\nabla b^n\|_2^2 dt &= - \lim_{n \rightarrow \infty} \int_Q \frac{\partial_t b^n + \nabla b^n \cdot \mathbf{v}^n}{b^n} + (b^n - 1) dx dt \\ &= - \int_Q \frac{\partial_t b + \nabla b \cdot \mathbf{v}}{b} + (b - 1) dx dt \\ &= \int_0^T \|\nabla b\|_2^2 dt\end{aligned}$$





Summary

- Thermodynamic approach (Rajagopal, Srinivasa (2000))
 - generates classes of the rate-type fluids satisfying the laws of thermodynamics
 - efficient even in a purely mechanical context for incompressible fluids (Maxwell, Oldroyd-B, Giesekus, Burgers)
 - compressible rate-type fluids (Málek, Průša (2017))
 - capable of developing models where different energy mechanisms take place
- PDE analysis for a simplified model with stress diffusion
 - long-time and large data existence of weak solution in 3D
 - a simplified model shares many qualitative features with general viscoelastic rate-type models with stress diffusion
 - presence of stress diffusion in Eq. for \mathbb{S} combined with the presence of Korteweg stress in Eq. for \mathbf{v}
 - non standard a priori estimates that would be difficult to find out without the thermodynamic approach presented

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Thank you for your attention.